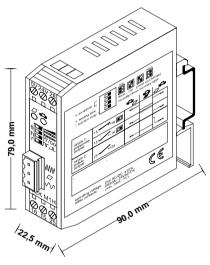


# **Operation Instruction VEK M1H**

## 1-channel induction loop detector for installation on DIN-rail



Please read these instructions and safety information and warnings attentively before initial operation of the detector!

## 1 General

#### Applications:

- · barrier controls
- · door and gate controls
- · parking and traffic technology

## Features:

The induction loop detector VEK M1H is a system for inductive recognition of vehicles with the following characteristics:

- · isolated transformer between loop and detector electronics
- · automatic calibration of the system after switching on
- · continuous rebalancing of frequency drifts
- · usable for single place parking space supervising
- · sensitivity independent of the loop inductivity
- · presence signal by LED display
- · potential free relay contacts for presence and pulse output
- · pulse output while leaving the loop
- · signalling of loop frequency by LED
- · loop connection plug-in for diagnosis

For planning and installation of loops please note our manual "detection of vehicles with the induction loop detector".

## 2 Setting options

#### 2.1 Sensitivity

The setting of the sensitivity calls the electronics to a value of frequency deviation which a vehicle must produce for setting the output of the detector. The sensitivity can be adjusted in 4 steps with the two DIP-switches 's' on top of the front panel.

sensitivi	ty step	DIP-switch 's'
1 low	(0,64% \( \Delta f/f \)	
2	(0,16% ∆f/f)	
3	(0,04% \( \Delta f/f \)	
4 high	(0,01% ∆f/f)	

#### 2.2 Hold time and Reset

The hold time can be adjusted with DIP-switch 'h'.

At the completion of hold time it will be displayed "free loop" and the detector calibrates automatically. The hold time starts with the occupation of the loop.

hold time	DIP-switch 'h'	
5 minutes		
infinite		

An automatic calibration of the loop frequency will be done by the detector after switch-on of the power supply. In case of short power cuts <0.1s there is no calibration.

A reset with calibration can be effected by changing the hold time

### 2.3 Operation principle of the presence relay

The detector has one relay for presence output and another relay for pulse output each with a potential free contact. The operation principle of the presence relay can be changed with the DIP-switch 'r'

operation principle presence relay	DIP-switch 'r'
contact normally closed	
contact normally open	

## 2.4 Frequency adjustment

The operation frequency of the detector can be adjusted in two steps by the 3-pole connection jack in the front panel. The permissible frequency range is 30kHz to 130kHz. The frequency depends on the loop inductivity (depending itself on: loop geometry, number of loop turns and loop lead) and the adjusted frequency step.

> upper position = high frequency lower position = low frequency

## 3 Outputs and LED

#### 3.1 Contact mode of the relays

The following table shows the state of the relay contacts depending on the detector mode.

detector mode	presence relay		pulse relay
free loop	close	open	open
covered loop	open	close	open
loop gets free	close	open	200ms pulse
loop failure	open	close	open
power off	close	close	open

In case of a loop failure the detector checks the loop condition cyclically and continues automatically after elimination.

#### 3.2 LED signals

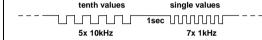
The green LED signals that the detector is ready for operation. Via the red LED, the activation of the relavs output is announced depending on the occupation status of the loop.

LED green loop control	LED red loop condition	detector function
off	off	power off
flashing	off	calibration or output of frequency
on	off	detector ready for operation, free loop
on	on	det. ready f. operation, covered loop
off	on	loop failure

#### 3.3 Output of loop frequency

Approx. 1 sec. after calibration of the detector the loop frequency will be displayed by pulse signals of the green LED. Firstly the 10kHz position of the frequency value will be indicated. For every 10kHz frequency value the green LED flashes once. After a break of 1sec the 1kHz position is displayed in the same manner. If there is value of '0' in the 1kHz position there will be displayed 10 flashes. The flashes for 1kHz position are a little bit shorter than for the 10kHz

Example for 57kHz loop frequency:



## 4 Safety information and warnings

- The device should only used for the applications described by the manufacturer.
- Please keep this operation instruction always accessible and hand it over to every user.
- Inadmissible modifications to the device, use of repair parts and supplementary equipment which are not sold or recommended by the manufacturer can cause burning, electric shock and injuries. Therefore the manufacturer has no liability and this excludes all demands of warranty
- The warranty regulations of the manufacturer are valid in the version of the purchase date for that device. There is no liability for not suitable, wrong manual or automatic adjustments also regarding no suitable applications of the device.
- Repairs may only made by the manufacturer.
- The power supply must be fulfill the requirements for SELV and limited power sources according to EN 60950-1.
- · All connections, the start-up, maintenance, measurements and adjustment operations to the detector have to be made from electrical specialists who have special know-how in the prevention
- · For the use of devices which have contact to electrical power, please pay attention to the valid security instructions and all prevention orders of fire and accidents.
- All operations with the device and its placement have to be done in accordance with national and general electrical instruction orders.
- The user is responsible for an installation, which has conformity to all technical rules in the country where the device is mounted, and also to all regional valid orders. For that the dimension of cabling, fuse protection, connection to around, switch off, disconnection, isolation controlling and the protection for overload current have to be regarded in detail.
- The detector can not be used as a security device regarding to the security instructions of electrical machines. Using in systems with high danger potential it is necessary to include additional protection devices !

#### 5 Technical data

Dimensions Protection class

Power supply

Operating temperature Storing temperature Humidity

Loop inductivity Frequency range Sensitivity

Hold time

Loop lead length Loop resistance

Relays presence relay pulse relav Signal duration Cycle time

Connections

79x22.5x90 mm (hxwxd without plug) 24V AC/DC +10% max.1.5W SELV

-20 °C to +70 °C -20 °C to +70 °C max, 95 % not condensing

25-800 µH, recommended 100-300uH 25-130 kHz in 2 steps

0.01 % up to 0.65 % (Af/f) in 4 steps

0,02 % up to 1,3 % (ΔL/L) 5 minutes or infinite

max. 250 m

max. 20 Ohm (incl. loop lead)

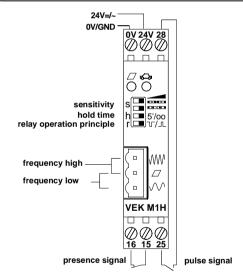
250mA / 24V AC/DC (min. 1mA/5V) contact n.c. (adjust. operation principle) contact n.o.

> 200 ms

40 ms (reaction time 80 ms)

screw terminals (power supply, relays) binder plug (loop connection)

## 6 Connections



#### Note

The information in this instruction can be changed without previous announcement

With this description all previous issues lose their validity.

The summary of information in this description was done with all possible acknowledge and by the best conscience.

FEIG ELECTRONIC can't give guaranty for the correctness of all information. Particularly there is no liability by FEIG ELECTRONIC for damages which result from a wrong installation of the device.

In spite of all efforts to correctness we are very thankful for every point to a mistake in this description.

The installation recommendations in this description are based on optimum conditions. For wrong environment conditions FEIG ELECTRONIC doesn't give a warranty to optimum operation of the

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